

The Salesman's Improved Paths

A $\frac{3}{2} + \frac{1}{34}$ approximation

Anke van Zuylen

based on joint work with András Sebő

Workshop on Flexible Network Design, Amsterdam

(Metric) $s - t$ Path TSP

Given:

- vertex set V
- special vertices $s, t \in V$
- distance metric $c : \binom{V}{2} \rightarrow \mathbb{Q}^{\geq 0}$

Find:

Minimum length path from s to t that visits every vertex in V .

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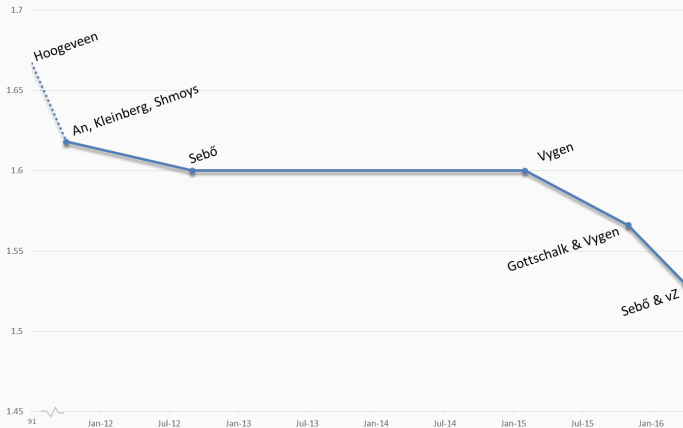
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Equivalent to solving $s - t$ path TSP:

Find a minimum cost “ $s - t$ tour” : a **connected** multigraph G in which **s, t have odd degree and every other vertex has even degree.**

$s - t$ Path TSP: Progress for General Metrics



Why does Christofides's algorithm not immediately give a $3/2$ -approximation?

Christofides for $s - t$ path TSP

Algorithm	Analysis
<ul style="list-style-type: none"><li data-bbox="130 433 932 471">• Connectivity: find a Minimum Spanning Tree S.<li data-bbox="130 481 891 626">• Degree parities: add a Min Cost T_S-join J_S: $s, t \in T_S$ if they have even degree in S, $v \in T_S$, if $v \in V \setminus \{s, t\}$ has odd degree in S.	

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	Total ???

LP Based Analysis: Subtour Elimination LP for $s - t$ Path TSP

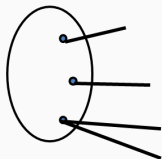
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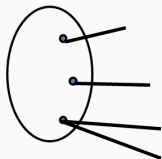
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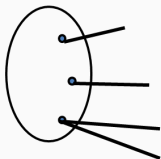


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- At least two edges in a non $s - t$ cut

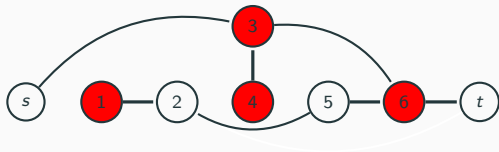
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Note: Feasible region is a subset of the spanning tree polytope $\Rightarrow c(S) \leq c(x^*)$.

LP Based Analysis: T_S -Join Polyhedron

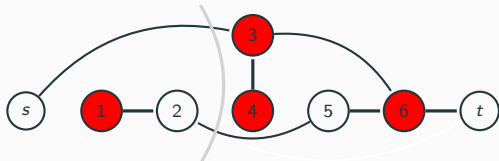
- $y(e)$ is a decision variable indicating whether e is used in the T_S -join, $y(e) \geq 0$
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at least one edge in $\delta(U)$
if $U \subset V$ has an odd
number of vertices in T_S

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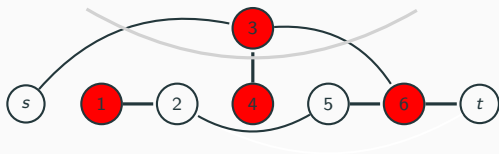
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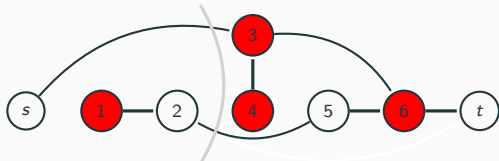
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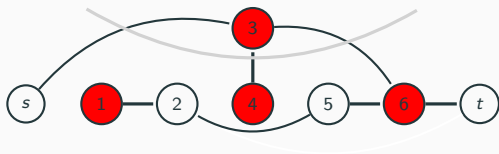
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Note: T_S -join polyhedron has integer extreme points \Rightarrow Can upper bound cost of minimum T_S -join by cost of any feasible y -vector.

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Wishful thinking: if $y = x^/2$ is feasible for the T_S -join polyhedron, then $c(y^*) \leq \frac{1}{2}c(x^*)$.*

Conclusion: no $3/2$ yet because...

$x^*/2$ will violate the join constraints for $s - t$ cuts Q such that

- Parity of tree S in Q is “wrong”: S has an *even* number of edges in Q , and
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Let the *deficit* for a narrow cut Q be $\left(\frac{2-x^*(Q)}{2}\right)$ “parts-of-an-edge” if $|S \cap Q|$ is even, e.g. an $s - t$ cut Q with $x^*(Q) = \frac{3}{2}$ has deficit $\frac{1}{4}$ if S is even across Q .

How to deal with even narrow cuts?

[AKS'12, S'12, V'14, GV'15]: **Best-of-Many Christofides**

- ✓ **Connectivity:** Decompose x^* into a collection of spanning trees \mathcal{S} (with multipliers $\lambda_S > 0, \sum_{S \in \mathcal{S}} \lambda_S = 1$).
- ✗ **Parity:** For each $S \in \mathcal{S}$: add a min cost T_S -join

[Gao'13]: **Gao tree** (for graph $s - t$ path TSP)

- ✗ **Connectivity:** Compute a minimum cost tree S_{Gao} that has $|S_{Gao} \cap Q| = 1$ for each narrow cut Q .
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[This work]: **Best-of-Many with Deletion**

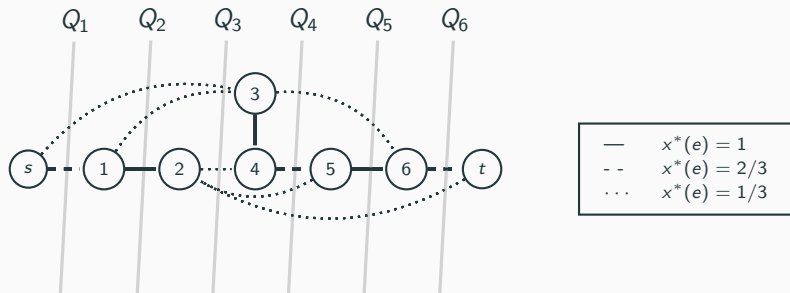
Main idea: For each cut Q , we

- “save” (compared to $c(S) + c(x^*)/2$) on trees S when $|S \cap Q| = 1$
- use the “savings” to make up for Q 's deficit in trees S' when $|S' \cap Q|$ is even.

Best-of-Many with Deletion

- Decompose x^* into a collection of spanning trees \mathcal{S} (with multipliers $\lambda_S > 0, \sum_{S \in \mathcal{S}} \lambda_S = 1$) using the Gottschalk-Vygen decomposition.
 - Gottschalk-Vygen guarantees: for narrow cut Q , $|S \cap Q| = 1$ in the “first” $2 - x^*(Q)$ fraction of the trees in the decomposition.
 - In those trees, we will call the edge in $S \cap Q$ “lonely”
- For each $S \in \mathcal{S}$:
 - Delete the “lonely edges”
 - **Correct parity** (with a join chosen from a specific distribution)
 - **Correct connectivity**: add back doubled lonely edges if needed.
- Output the solution with minimum cost.

Illustration: LP Solution



Example from Gao'15:

- Narrow cuts are indicated by gray lines and labeled Q_1, \dots, Q_6 .
- $x^*(Q_1) = x^*(Q_6) = 1, x^*(Q_i) = \frac{5}{3}$ for $i = 2, 3, 4, 5$.

Illustration: Gottschalk-Vygen Decomposition into Trees

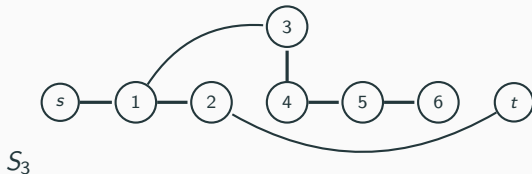
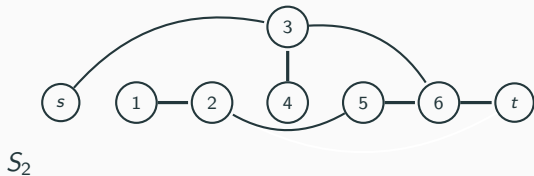
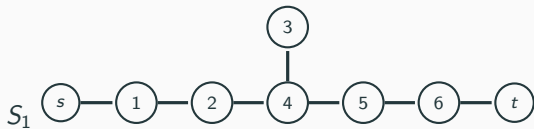
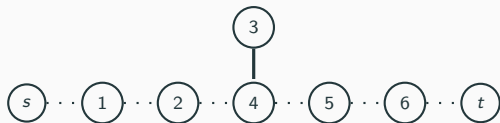


Illustration: Algorithm Executed on Gao-Tree S_1

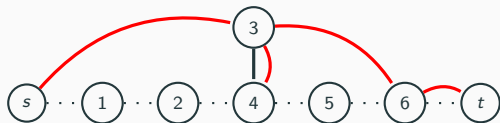


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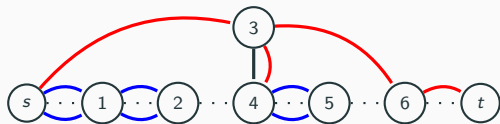
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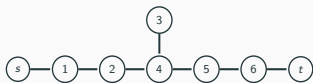
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Analysis of Solution Based on S_1

s-t tour



Forest

Parity Correction

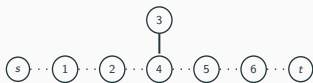
Connectivity Correction

S_1

Total

Analysis of Solution Based on S_1

s-t tour



Forest

Parity Correction

Connectivity Correction

S_1

$-L_1$

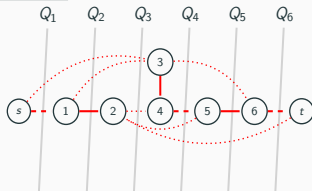
Total

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s-t tour



Average T_F -join



Forest

Parity Correction (average)

Connectivity Correction

S_1

$-L_1$

$$\frac{x^*}{2} +$$

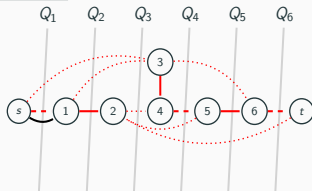
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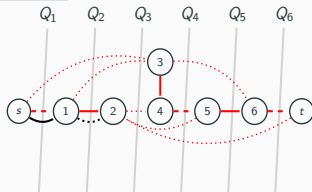
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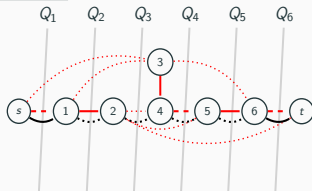
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— 1/2
 ··· 1/3
 ···· 1/6

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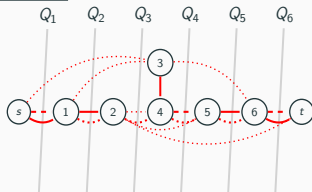
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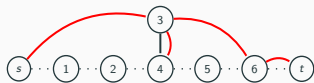
S_1

$$\frac{x^*}{2} + \sum_{i=1}^6 \frac{2-x^*(Q_i)}{2} (L_1 \cap Q_i)$$

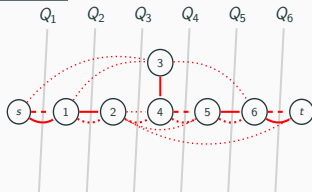
Total

Analysis of Solution Based on S_1

s-t tour



Average T_F -join



Forest

Parity Correction (average)

Connectivity Correction

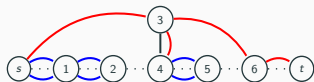
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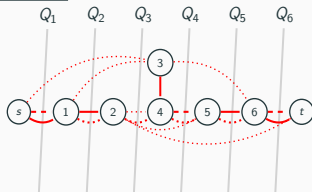
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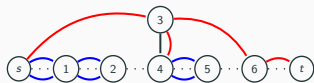
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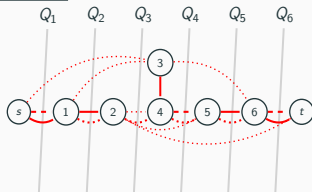
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Average T_F -join



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Parity Correction (average)

Connectivity Correction

S_1

$$\frac{x^*}{2} +$$

$-L_1$

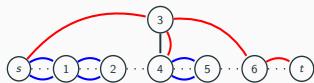
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$$\sum_{i=1}^6 (x^*(Q_i) - 1) (L_1 \cap Q_i)$$

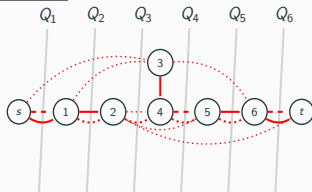
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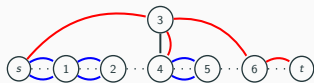
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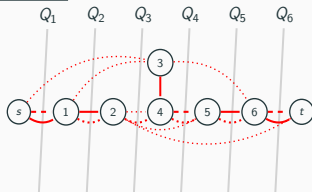
Total

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s-t tour



Average T_F -join



Forest

Parity Correction (average)

Connectivity Correction

S_1

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Total

$S_1 + \frac{x^*}{2}$

$$- \sum_{i=1}^6 \frac{2-x^*(Q_i)}{2} (L_1 \cap Q_i)$$

How deletion helps

Consider a given narrow cut Q :

- Can show in general:

If S has a lonely edge in Q , deletion allows us to “save”
 $\left(\frac{2-x^*(Q)}{2}\right)$ -parts-of-an-edge from the total $S + \frac{x^*}{2}$.

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Theorem (SvZ'16)

Let x^* be an optimal solution to the subtour LP, such that no cut Q has $x^*(Q) \in (\frac{3}{2}, 2)$. Then there exists an $s - t$ tour of cost at most $\frac{3}{2}c(x^*)$.

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Solution: Increase savings and decrease deficits by increasing our base line:

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Can show: If $\gamma = \frac{1}{16}$, then savings can always pay for the deficits.

Lemma (SvZ'16)

Let x^* be an optimal solution to the subtour LP, and given a decomposition of x^* into spanning trees \mathcal{S} , let p^* be the average of the incidence vectors of the $s - t$ path in \mathcal{S} . There exists an $s - t$ tour of cost at most $\frac{3}{2}c(x^*) + \frac{1}{16}c(p^*)$.

Improved Result for General Case

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Observation (Hoogeveen'91, Sebö'12)

Let x^* be an optimal solution to the subtour LP, and given a decomposition of x^* into spanning trees S , let p^* be the average of the incidence vectors of the $s - t$ path in S . There exists an $s - t$ tour of cost at most $2c(x^*) - c(p^*)$.

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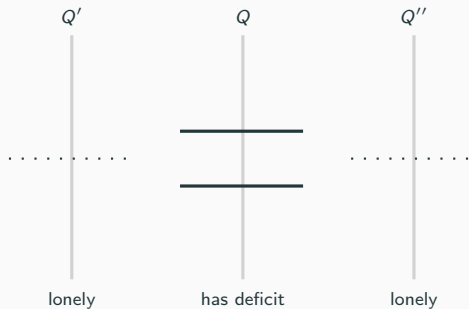
The minimum of the above two tours has cost at most $(\frac{3}{2} + \frac{1}{34})c(x^*)$.

What I did not show you (but did use):

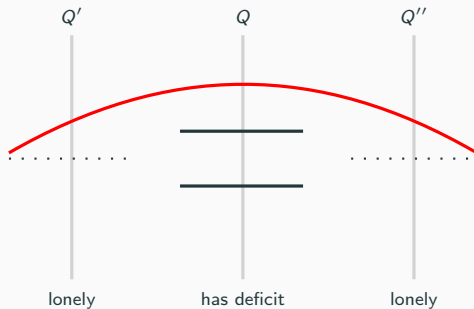
how to prove that **Connectivity Correction** can be done using at most

$$\sum_{Q \text{ lonely in } S} (x^*(Q) - 1)(L \cap Q)$$

A few details on the proof: need for Gottschalk-Vygen

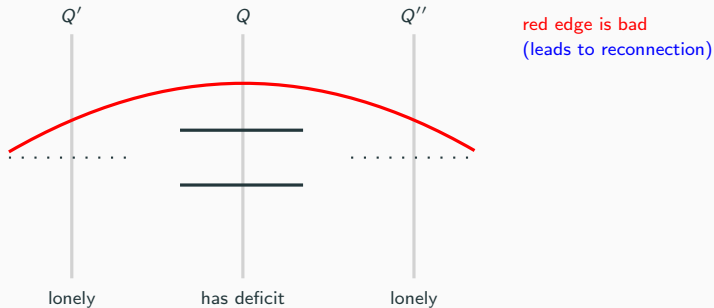


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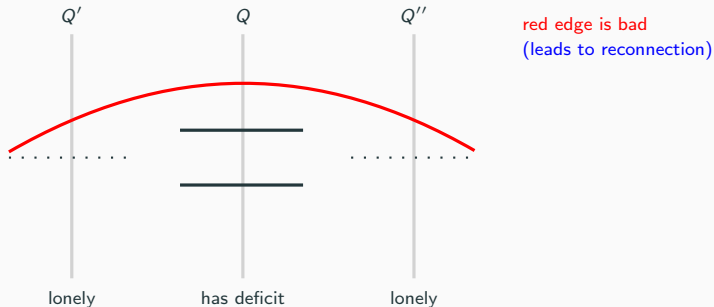
red edge is bad
(leads to reconnection)

A few details on the proof: need for Gottschalk-Vygen



GV guarantees that Q 's *saved* edge-parts are not bad:

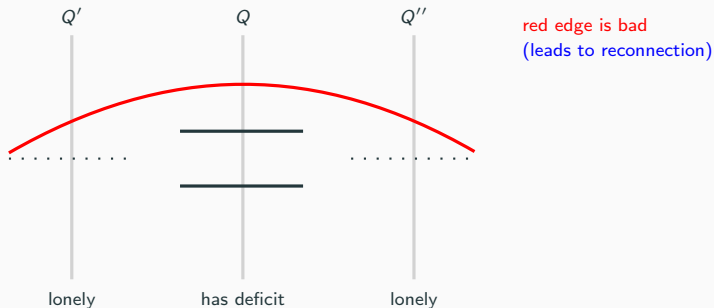
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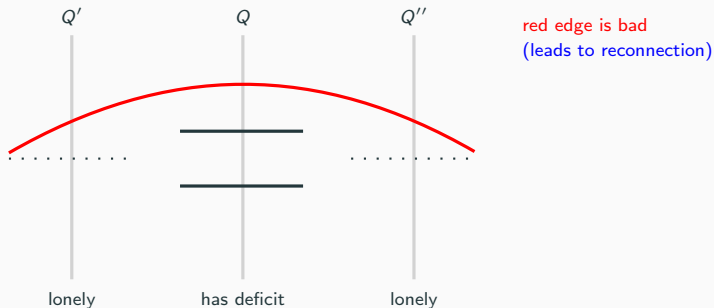
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GV guarantees that Q' 's saved edge-parts are not bad:

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- In those trees Q' , Q'' were also lonely.

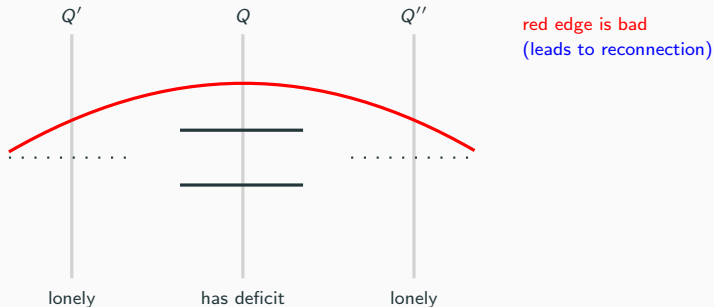
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- But then Q 's saved edge-parts cannot cross Q' and Q'' .

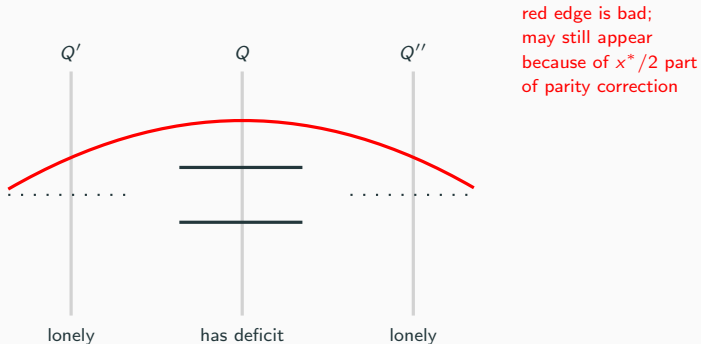
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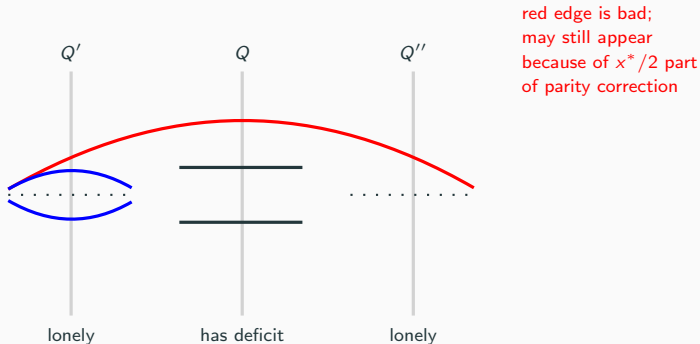
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- ⇒ Q 's saved edge-parts are not bad.

A few details on the proof: LP for reconnection



For each bad edge (that crosses more than one cut with a lonely edge), we double all but one of the lonely edges to reconnect.

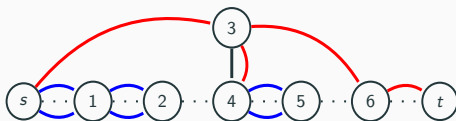
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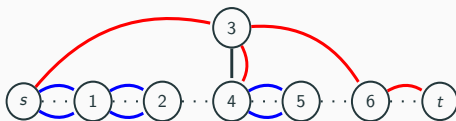
The solution to a linear program is used to decide *which* lonely edges are used for reconnection (only needed to “spread things out” for the analysis: the algorithm may use the cheapest lonely edges).

Conclusion



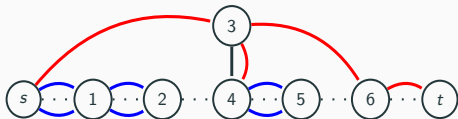
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Conclusion



- Approximation guarantee and integrality gap bound of $\frac{3}{2} + \frac{1}{34}$
- Mixing **Parity** and **Connectivity** stages in new ways leads to benefits!
- Open question: Shave off the remaining $+\frac{1}{34}$ from the ratio.

Questions??